FORM **CUSTOMIZED GRIPPERS** [ED. 01].

Company _____

Email _____

Phone _____

F·IPA
challenge accepted

Please fill out the following questionnaire carefully so we can select the right product for you. Please note that we can only guarantee the best choice for you if all information is completely available. If important information is missing, we will contact you. You can complement this information with photographs, 3D files, etc.

Robot-Gripper Interface

Robot type _____

Handling type

☐ Linear

☐ Swivel axes [no. of axes] _____

☐ Delta robot [3-leg]; FlexPicker

Model name

_____

☐ Other _____

Media supply

Nr of vacuum circuits _____

Nr of compressed air circuit _____

[bar] _____ [psi] _____

Hose diameter [mm] _____

Hose length [mm] _____

Vacuum generation

☐ by FIPA   by the customer

☐ Nr of ejectors [model] _____

☐ Pump [model] _____

☐ Side channel blower [model]

_____

☐ Other _____

Comments

_____

_____

Application

Type of product to be handled _____

Product weight [g] _____

Product dimensions [LxWxH] [mm] _____

CAD available   ☐ yes   ☐ no

Item picked from

☐ Conveyor belt

☐ Pallet

☐ Container

☐ Tray

☐ Fixture

☐ Other

Item placed on

☐ Conveyor belt

☐ Pallet

☐ Container

☐ Tray

☐ Fixture

☐ Other

Cycle time

Pick-up [sec.] _____

Placement [sec.] _____

Description of application _____

Send to:
comercial@fluidotronica.com
For more information:
+351 256 681 957
www.fluidotronica.com

FiPA
challenge accepted

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Gripper Design

Integrated vacuum generation required ☐ yes ☐ no

Media feed-through required ☐ yes ☐ no

Interference contours [e.g. gripping space between products]

_____

_____

Labelling _____

Colouring _____

Special cleaning regulations _____

Description of process

_____

_____

_____

Current solution

_____

_____

_____

_____

_____

Improvements required

_____

_____

_____

_____

_____